

#### **Aerial Surveys with Drones within NBPOL**

A Story of Innovation Will Unsworth 8<sup>th</sup> November 2019







- Precision Agriculture
- Ensures that our inputs (labour, machinery, etc.) to the plantation are exactly as required
  - Excess is a waste
  - Inadequate is a loss
- Precision avoids waste while optimizing outputs (crop)





Innovations

- A new approach to collect data
- A new approach to processing data
- A new approach to reporting data
- A new approach to using data





- Respect to the original innovators!
  - William Griffiths
  - David Mather
  - Mike Jackson
  - Brian Cazalet
  - Richard Tiamu
  - Dr Luc Bonneau
  - Solomon Sar





# **Fertiliser Planning**

Limited







Kg/p	Stems Per Hectare (SPH)	Required Kg of Fertiliser 192	
1.5	128	180	Excess supply (6%)
1.5	120	202.5	Short supply (5%)
1.5	135	202.0	

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- Cost of over-ordering
  - High stock levels
  - Storage costs
  - Double handling
  - Losses (Spoilage and Theft)

- Costs of under-ordering
  - Under-fed palms
  - Yield losses
  - Additional orders
  - Opportunity costs of inputs

#### Straightforwards



Harder to quantify



- NBPOL
  - 91,081 ha of Oil Palm in PNG and SI (31 Dec 2018)
  - 11,361,688 palms in PNG and SI
  - 4.41kg/palm (2018 average for all palms)
  - 50,100 tonnes of fertiliser (2018)
  - ~USD 20 million per year in fertiliser expenditure



# **Fertiliser Planning**





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- Utilise drones to generate aerial imagery of the plantations and allow for computer based counting of in-field palms
- Generate an accurate palm stand census to ensure that the correct fertiliser volumes are ordered







#### **Progress To Date**







 The first overwhelming option (even several years ago) was which way to go first. Two broad options were available





 Fortunately, there were differing opinions, and 2 groups went with different options





- Drones were selected based on
  - Cost
  - Support and Training
  - Processing capabilities
  - Perceived quality of product
- Most of our expectations were wrong
  - Technology moved around us
  - Reliance on others could not be sustained





- Again, 2 groups went in different directions
- Proprietary Flight Planning Software
  - Single package of software, but multiple internal modules for each stage of the process
- Open Source Flight Planning Software
  - Multiple software packages with links and conversions in-between
- Both suffered from continuous updates, in areas with limited internet access this cost a LOT of time



#### **How to Fly Drones?**







# **How to Fly Drones?**



One Survey – 30-1,000 ha – 1-20 flights – 400-500

photos per flight









- Similarly to the flight planning, we used one system tied to the drone manufacturer, and one off-the-shelf graphics program for stitching together images
- One site worked on their desktops
- One site invested in a high-spec workstation for data processing





- One site used the proprietary automated (image recognition) palm counting software
- One site hired a team to manually count palms onscreen with large screens and even touch screens
- Both require immense amounts of checking and double checking. False positives, false negatives, whoopsies and do-overs





Team 1	The 'A' Team	Team 2
Quad Copter	$\rightarrow$	Fixed Wing
Recreational Drone		Commercial Drone
Open Source flight planning software	$\rightarrow$	Proprietary flight planning software
Manual Palm Counts	3 <sup>rd</sup> Way	Automatic Counts
Workstation		Desktop Computer





- Finally, we have
  - A stitched ortho-photo of a block (6GB)
  - A series of points on a map
  - A number (number of palms)
  - A number (palm density)
- We have data (which we love)
- But not information yet (that our managers are waiting for)



# How to Deliver the Data



- Reports
- Data delivery through file sharing
- Conversion into Google Earth for ease of access





# How to Deliver the Data





 Heat Maps to show consistency of planting

 Using measurements to develop indexes to reduce the amount reporting



#### **Outcomes**





# **Findings**





#### What is Next?





# Thank you



